

Service ID

Location France



Qualification of trajectory execution accuracy of crop production robots (

Provider service

INRAE

Link to content

<https://agrifoodtef.eu/services/qualification-trajectory-execution-accuracy-crop-production-robots-outdoor-mobility>

Type of Sector

Arable farming, Greenhouse, Horticulture, Tree Crops, Viticulture

Accepted type of products

Design / Documentation, Physical system, Other

Type of service

Collection of test data, Performance evaluation, Test design, Test execution, Test setup

Description

The test assesses the accuracy of crop production robots in following precise paths across different terrains, simulating typical agricultural tasks. The test uses advanced laser tracking to measure how well the robot follows a set trajectory, including straight and curved paths, on slopes and amidst obstacles. This enables manufacturers to ensure that their robots meet performance standards for real-world field operations. A detailed report is provided, helping optimise robot performance for outdoor mobility in agricultural settings. A manufacturer's representative must oversee the process. This test is part of a series known as ARPA: Agricultural Robot Performance Assessment. It is identified as ARPA n (where n is 1, 2, 3, etc.) for tests that focus on safety functions and as ARPA XXn for other performance evaluations.

How can the service help you

The ARPA PC1 test helps manufacturers verify their robots can precisely navigate complex agricultural environments. Before testing, manufacturers may face uncertainty about their robot's performance on uneven terrain or around obstacles. After testing, they gain detailed feedback on how their robot handles different real-world scenarios, helping them address shortcomings and improve system accuracy. This service bridges the gap between development and field deployment, ensuring robots meet the demanding requirements of modern crop production. The test report is prepared and reviewed by the test operator. This document belongs exclusively to the customer, satisfying the need for unbiased operational confidence.

How the service will be delivered

Customising the ARPA PC1 test offers significant benefits, allowing you to simulate typical working environments precisely. You can test paths at different angles (e.g., 30°, 45°, 90°) or with varying row widths between crops. However, it's important to note that all technical details must be discussed beforehand, and complex configurations may require additional preparation time.

The ARPA PC1 test must be done with a manufacturer's technical representative present. Their presence helps ensure the test is accurate and addresses any technical difficulties. Additionally, providing technical manuals in advance is a requirement for the test. It's crucial to plan for the ARPA PC1 test. For instance, conducting the tests during the winter may not be possible, so customers should plan accordingly. This foresight will ensure a smooth testing process and accurate results.

Service customisation

ARPA PC1 employs a laser-based tracking system to measure the robot's trajectory execution accurately. The test consists of multiple runs on a predefined path incorporating various terrain configurations and obstacles to replicate real-world agricultural conditions effectively.

Testing is available year-round, with possible restrictions during the winter season due to soil and weather conditions. Each test lasts approximately five days, depending on the conditions established during the technical meeting, and is carried out on the premises of INRAE - Montoldre - AgroTechnoPôle in France (just two hours from Lyon).

A manufacturer's representative must oversee the process to ensure the machine operates correctly during testing. The robot's technical and user manuals must be submitted in advance. Customers will receive a detailed technical report on the test. This service is aimed at manufacturers of agricultural robots and safety systems.

This test is part of an ARPA: Agricultural Robot Performance Assessment series. It is identified as ARPA n (where n is 1, 2, 3, etc.) for tests focusing on safety functions and as ARPA XXn for other performance evaluations.